

MA2





Product Segments

Industrial Motion

TiMOTION's MA2 series electric linear actuator was specifically designed for applications that face harsh working environments and require heavy-duty and durability. Its IP69K protection ensures it will withstand high-pressure water jets and the ingress of dust and other solid contaminants. The MA2 electric cylinder actuator also has optional Reed switches along the outer tube which allow users to adjust the stroke length. For improved control and accuracy of motion, the MA2 can be customized with many different feedback options depending on your application requirements. Example applications suitable for the MA2: Agricultural equipment such as spreaders, harvesters, grain handlers, combines, and tractors. Commercial and industrial applications such as commercial lawn mowers, scrubbers and sweepers, material handling equipment and livestock ventilation systems.

General Features

Max. load 6,000N (push/pull)

Max. speed at max. load 5.8mm/s
Max. speed at no load 52.5mm/s

Retracted length ≥ Stroke + 131mm

IP rating IP69K Certificate UL73, EMC Stroke \geq 25~1000mm

Options Hall sensors, POT, manual drive, Reed sensor

on the outer tube

Voltage 12V DC, 24V DC, 36V DC;

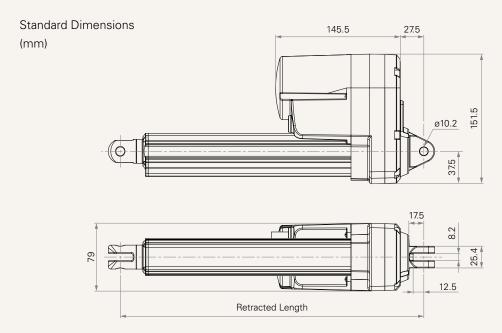
12V DC, 24V DC, 36V DC (thermal control)

Operational temperature range Operational temperature range

at full performance

-30°C~+65°C +5°C~+45°C

Drawing



Load and Speed

CODE	Load (N)		Self Locking	Typical Current (A)		Typical Speed (mm/s)	
	Push	Pull	Force (N)	No Load 24V DC	With Load 24V DC	No Load 24V DC	With Load 24V DC
Motor Spee	d (5200RPM, du	ty cycle 25%)					
F	1000	1000	1300	2.7	5.8	52.5	44.7
G	2000	2000	2600	2.4	5.7	25.5	21.8
Н	4000	4000	5200	2.3	5.9	13.2	11.0
J	6000	6000	7800	2.0	4.8	6.6	5.8

Note

- 1 Please refer to the approved drawing for the final authentic value.
- 2 This self-locking force level is reached only when a short circuit is applied on the terminals of the motor. All the TiMOTION control boxes have this feature built-in.
- 3 The current & speed in table are tested with 24V DC motor. With a 12V DC motor, the current is approximately twice the current measured in 24V DC. With a 36V DC motor, the current is approximately two-thirds the current measured in 24V DC. Speed will be similar for all the voltages.
- 4 The current & speed in table are tested when the actuator is extending under push load.
- 5 The current & speed in table and diagram are tested with a stable 24V DC power supply.
- 6 Standard stroke: Min. ≥ 25mm, Max. please refer to below table.

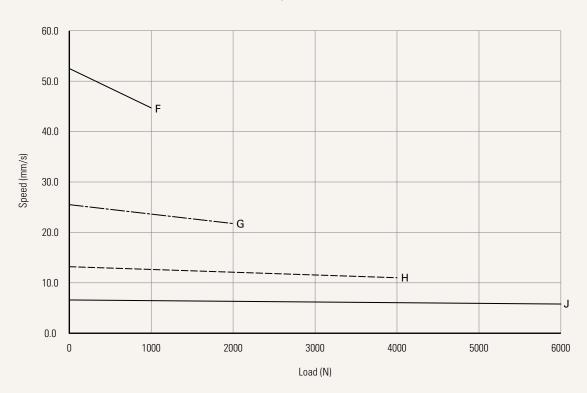
CODE	Load (N)	Max Stroke (mm)
H, J	≥ 4000	600
G	= 2000	800
F	= 1000	1000



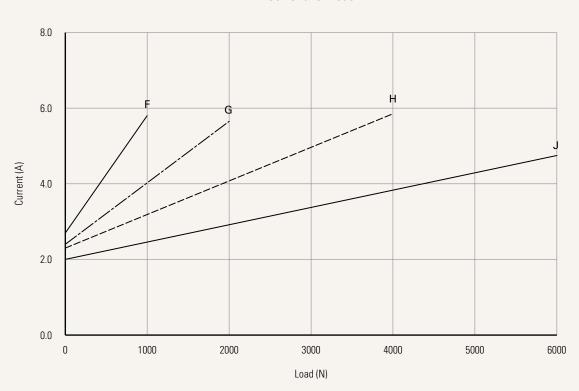
Performance Data (24V DC Motor)

Motor Speed (5200RPM, Duty Cycle 25%)

Speed vs. Load



Current vs. Load





MA2 Ordering Key



MA2

Version: 20201208-F

				version. Zuzutz	
V oltage	1 = 12V DC		5 = 24VDC, thermal pro	tector	
	2 = 24V DC		6 = 12VDC, thermal pro	tector	
	3 = 36V DC		7 = 36VDC, thermal pro	tector	
Load and Speed	See page 2				
Stroke (mm)	See page 2				
Retracted Length mm)	See page 5				
Rear Attachment		clevis U, slot 8.2, depth 12.5, h			
mm)	•	clevis U, slot 8.2, depth 15.0, h			
See page 6	· ·	clevis U, slot 8.2, depth 15.0, h			
		clevis U, slot 8.2, depth 15.0, h			
Front Attachment		n punched hole, without slot, h			
(mm)		n punched hole, without slot, h			
See page 6		n punched hole, without slot, h			
	=	clevis U, slot 8.2, depth 15.0, h			
	· ·	clevis U, slot 8.2, depth 15.0, h			
	=	clevis U, slot 8.2, depth 15.0, h	nole 12.8		
	K = Rod end bearing, h	ole 12.8			
Direction of Installation (Counterclockwise)	1 = 90°	2 = 0°			
See page 6					
Functions for	1 = Two switches at fu	II retracted / extended position	s to cut current		
Limit Switches		II retracted / extended position		between to send signal	
		II retracted / extended position		Ü	
	6 = Two switches at fu	II retracted / extended position	s to cut current + send signal		
Reed Sensor on the Outer Ttube	0 = Without	1 = Reed sensor*1	2 = Reed sensor*2		
Output Signal	0 = Without	1 = POT	5 = Hall sensor*2		
Connector	2 = Tinned leads				
See page 7					
Cable Length (mm)	1 = Straight, 500	2 = Straight, 1000	3 = Straight, 1500	4 = Straight, 2000	
P Rating	1 = Without	3 = IP66	8 = IP69K		
	2 = IP54	6 = IP66D			
Manual Drive	1 = With				
T-Smart	0 = Without				

MA2 Ordering Key Appendix



Retracted Length (mm)

- 1. Calculate A+B+C = Y
- 2. Retracted length needs to \geq Stroke + Y

A. Rear/ Front	Attachment				
Front	Rear Attachment				
Attachment	1	2, 3, 4			
1, 2, 3	+131	+134			
4, 5, 6	+161	+164			
K	+178	+181			
C. Output Sign	al				
0, 5	-				
1	+20				

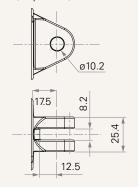
B. Stroke (mm)	
25~150	-
151~200	-
201~250	+10
251~300	+20
301~350	+30
351~400	+40
401~450	+50
451~500	+60
501~550	+70
551~600	+80
601~650	+90
651~700	+100
701~750	+110
751~800	+120
801~850	+130
851~900	+140
901~950	+155
951~1000	+160

MA2 Ordering Key Appendix

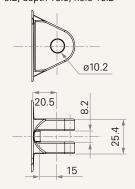


Rear Attachment (mm)

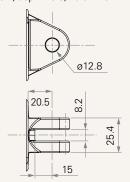
1 = Aluminum casting, clevis U, slot 8.2, depth 12.5, hole 10.2



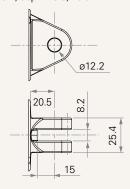
2 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 10.2



3 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 12.8

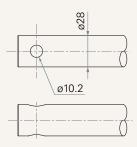


4 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 12.2

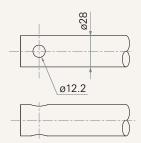


Front Attachment (mm)

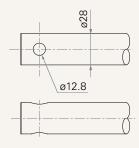
1 = Iron inner tube with punched hole, without slot, hole 10.2



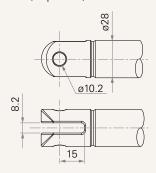
2 = Iron inner tube with punched hole, without slot, hole 12.2



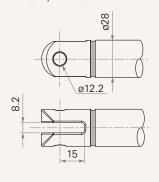
3 = Iron inner tube with punched hole, without slot, hole 12.8



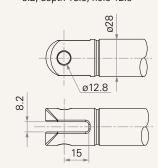
4 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 10.2



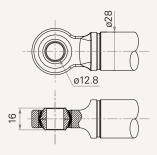
5 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 12.2



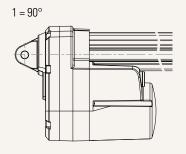
6 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 12.8

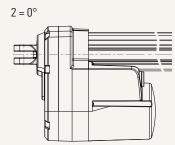


K = Rod end bearing, hole 12.8



Direction of Rear Attachment (Counterclockwise)



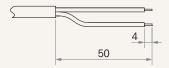


MA2 Ordering Key Appendix



Connector

2 = Tinned leads



Terms of Use